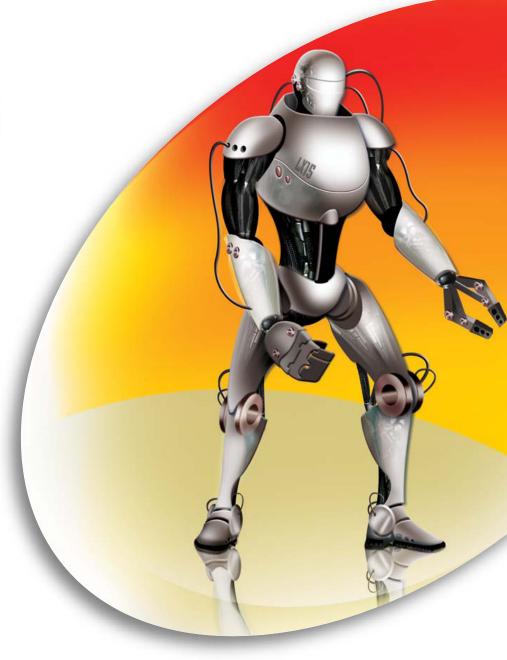
# Lexium® 15

Servodrives and servomotors
Perhaps a little too *smart!* 











## **Lexium® 15 Servodrives**

# Adaptable

## without compromise!

- From 0.9 kW to 42.5 kW.
- 4 configurable logic inputs and 2 configurable logic outputs, extendable using option cards
- 2 analog inputs.
- Integrated position indexer.
- 8 operating modes as standard.
- Integral EMC filter and braking resistors.

Lexium 15, comprising 3 servo drive models, is suited to all your needs.

### Lexium 15 Servo Drive LP (Low Power)

- From 0.9 kW to 4.3 kW.
- 1.5 A / 3 A and 6 A on 3-phase 200 V to 480 V.
- 3 A / 6 A and 10 A on 1-phase or 3-phase 230 V.
- 200 programmable motion tasks.

## Lexium 15 Servo Drive MP (Medium Power):

- From 5.7 to 11.4 kW.
- 10 A / 14 A and 20 A on 3-phase 200 V to 480 V.
- 180 programmable motion tasks.

## Lexium 15 Servo Drive HP (High Power):

- From 22.3 to 42.5 kW.
- 40 A / 70 A on 3-phase 200 V to 480 V.
- 180 programmable motion tasks

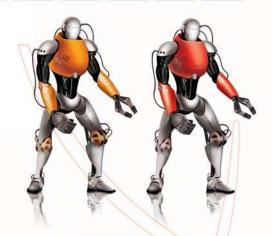
# Selection guide





0.00														
0			200240 V 1-phase and 3-phase			208480V 3-phase			208480V 3-phase			208480V 3-phase		
			LXM15L			-			LXM15N			LXM15H		
	Mo (Nm)	RPMmax	D13M3	D21M3	D28M3	D60N4	D10N4	D17N4	D28N4	D40N4	D56N4		C20N4X	
BSH 0551P	0.5	6880	1.4 Nm			1.4 Nm								
0551T	0.5	8000	1.4 Nm					1						
0552M	0.9	6160				2.25 Nm								
0552P	0.9	8000	2.7 Nm			2.26 Nm								
0552T	0.9	5920	2.54 Nm										11	
0552M	1.3	4880				3.5 Nm						*		
0552P	1.3	8000	4.2 Nm				3.87 Nm							
0701P	1.41	8000	2.66 Nm			2.66 Nm								
0701T	1.36	4880	3.19 Nm	3.19 Nm			2.91 Nm							
0702M	2.12	4960				5.63 Nm								
0702P	2.12	8000	5.63 Nm				4.85 Nm							
0702T	2.12	8000		5.45 Nm				4.47 Nm						
0703P	2.83	8000		9.28 Nm				7.71 Nm			-			
0703T	2.83	8000			7.38 Nm									
1001P	3.39	3780		7.08 Nm			6.19 Nm							
1001T	3.39	6000			8.5 Nm		Ì							
1002P	5.52	6000		14.79 Nm				12.13 Nm						
1002T	5.52	5340			11.59 Nm									
1003M	7.76	2640					15.19 Nm	22.95 Nm						
1003P	7.76	6000			19.69 Nm				19.69 Nm	23.17 Nm			k	
1004M	9.31	2400					19.8 Nm	29.87 Nm		34.17 Nm				
1004P	9.31	4800							25.7 Nm	33.83 Nm				
1004T	9.31	4080								21.04 Nm				
1401M	11.4	2360							26 Nm					
1401P	11.4	4000							23.33 Nm	23.33 Nm				
1401T	11.4	3920									23.33 Nm		1	
1402M	19.2	2360								47.5 Nm		j (		
1402P	19.2	4000					1			39.33 Nm	47.5 Nm			
1403M	25.4	2200								71.67 Nm				
1403P	25.4	4000									57.32 Nm			
1404M	32.1	2040								82.32 Nm	95 Nm			
2051M	36	2200								68.33 Nm	68.33 Nm	68.33 Nm		
2051P	36	3500										82 Nm		
2051T	36	3724										69.95 Nm	82 Nm	
2052M	65	2190										200 Nm	200 Nm	
2052P	65	3000										118.54 Nm	193.45 Nm	
2053M	90	2190										227.18 Nm	300 Nm	
2052P	90	3000											202.96 Nm	





1.4 Nm = Value in Nm corresponding to the peak stall torque of the servodrive-motor combination

RPMmax = Maximum speed Mo = Nominal stall torque in Nm



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			LCXIUIII I	Lexium 15 servodrives									
			200240 V 1-phase and 3-phase			208480V 3-phase			208480V 3-phase				
To the same of the	Mo (Nm)	RPMmax	D13M3	D21M3	D28M3	D60N4	D10N4	D17N4	LXM15N D28N4		D56N4		
BDH 0401B	0.18	8000	0.61 Nm										
0402C	0.31	8000	1.08 Nm										
0403C 0582C	0.41 0.84	8000 8000	1.46 Nm			0.24 Nov.	-	-					
0582E	0.84	8000	2.42 Nm	-		2.34 Nm	-	-	-				
0583C	1.13	8000	2.42 ((11)			3.2 Nm		1					
0583D	1.16	6540	3.58 Nm				3.58 Nm						
0583F	1.18	8000		3.52 Nm									
0584C	1.38	8000		Ü		3.94 Nm							
0584D	1.41	5420	4.4 Nm				4.4 Nm						
0584F	1.42	8000		4.46 Nm									
0701C	1.15	8000				3.34 Nm							
0701E	1.2	8000	3.24 Nm	1		5 74 N							
0702C 0702D	2.04	8000 3750	6.51 Nm			5.74 Nm	C E4 Non						
0702H	2.04	8000	0.51 MIII	5.36 Nm			6.51 Nm						
0703C	2.71	8000		3.30 MIII		7.83 Nm	1	1					
0703E	2.79	3140	8.55 Nm			oo-Aiii	8.55 Nm						
0703H	2.88	6630		7.35 Nm									
0841C	1.95	6630				5.12 Nm							
0841E	2.02	6630	5.33 Nm				5.13 Nm						
0841H	2.06	6630		4.78 Nm									
0842C	3.35	6630				9.37 Nm							
0842E	3.42	6630	9,72 Nm				9.41 Nm						
0842G	3.53	6630		9.56 Nm				8.66 Nm					
0842J	3.56	6630			7.56 Nm				7.56 Nm				
0843E	4.7	6630		40.01			11.7 Nm	44.00.11					
0843G 0843K	4.8	6630 6630		13.2 Nm	0.00 Nm			11.68 Nm	0.00 No.				
0844E	4.9 5.76	6630		-	9.02 Nm		4.4.4 Non	-	9.02 Nm				
0844G	5.88	6630		16.1 Nm			14.1 Nm	13.97 Nm			_		
0844J	6.0	6630		10.1 14111	12.18 Nm			10.97 14111	12.18 Nm				
1081E	4.7	4010					10.71 Nm		12.10 1111				
1081G	4.75	6000		10.82 Nm				10.82 Nm					
1081K	4.9	6000			9.22 Nm				9.22 Nm				
1082E	8.34	2470					18.08 Nm						
1082G	8.43	3840		19.51 Nm				19.51 Nm					
1082K	8.6	3840		j t	16.9 Nm				16.9 Nm				
1082M	8.6	3000		1						16.7 Nm			
1083G	11.4	2880						25.8 Nm					
1083K	11.6	2880			22.9 Nm				22.9 Nm	00.4.11			
1083M 1083P	11.4	2000								22.1 Nm	00.0 N		
1084G	11.4 14.3	3000 2390		-		-		31.7 Nm			22.2 N		
1084K	14.4	4000			28.1 Nm		1	31.7 WIII	28.1 Nm		-		
1084L	14.1	4000		-	20.111111		-		20.1 NIII	27.28 Nm			
1084N	14.1	4000								-21120 MIII	25.5 Ni		
1382G	11.9	1860						25.6 Nm					
1382K	12.2	4500			22.7 Nm				22.7 Nm				
1382M	12.2	4500								22.8 Nm			
1382P	12.3	4500									23.2 N		
1383G	16.5	1860						38.4 Nm					
1383K	16.8	3500			31 Nm				31 Nm				
1383M	17	3500								31.4 Nm			
1383N	17	4500									34.8 N		
1384K	20.8	2500							41.2 Nm	44 O No.			
1384L 1384P	21	2500 3500								41.9 Nm	40.0 N		
1384P 1385K	20.4	2200							46.8 Nm		40.2 N		
1385M	25	2200					-	-	40.0 NIII	47.6 Nm			
1385N	24.3	3000								TT.O MIII	50.2 N		
1882K	29.7	1800							59.4 Nm		00.Z IV		
1882M	30	1800								59.8 Nm			
1882P	29.4	2500									58.4 N		
1883M	42	3500								80.7 Nm			
1883P	41.6	1800									79.4 N		
1884L	53	2800								108 Nm			
1884P	52.5	1400									106 Nn		

1.4 Nm = Value in Nm corresponding to the peak stall torque of the servodrive-motor combination

RPMmax = Maximum speed

Mo = Nominal stall torque in Nm

Used in combination, Telemecanique products provide quality solutions, meeting all your Automation & Control applications requirements.



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# Simply Smart!

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